

28 Amp Digital High Frequency PWM Motor Speed Controller SPD-328-D and SPD-328-DS

The SPD-328-D(S) PWM controller allows you to control the speed of a motor, brightness of a lamp or other load using a potentiometer, an analog voltage level (0-5V), push buttons or logic level pulses. Use of PWM and low on-resistance MOSFETs allows for high efficiency control with minimal power loss. High frequency switching eliminates audible PWM noise when used with motors.

Absolute Maximum Ratings:

Parameter	Max	Units
Continuous Output Current	28	A
Instantaneous Output Current	40	A
Input Voltage	30	V

Warning – operating at or above the absolute maximum ratings may damage your controller or your equipment under control.

Operating Parameters:

Parameter	Min	Typical	Max	Units
Input Voltage	5.5	--	30	V
Input Voltage, Transient Low (0.5 sec)	0	--	--	V
Continuous Output Current	--	--	28	A
Digital Logic Input Low Level	0	--	1.5	V
Digital Logic Input High Level	3.5	--	5	V
Digital Input Capacitance	--	0.1	--	uF
Analog Voltage Input	0	--	5	V
Digital Pushbutton Mode Change Rate	--	33	--	% / s
Soft Start from Disabled Mode, Ramp Rate	--	100	--	% / s
PWM Frequency	18	20	22	kHz
Quiescent Current Drain	5	7	10	mA
Heatsink Temperature	-40	25	+100	°C


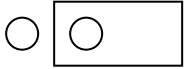
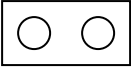

Pin-out:

Pin Label	Function	Active H/L	Mode
EN	PWM output enable (internal pull-up)	H = enable L = disable	Both
UP	Increase Pulse Width (internal pull-up)	L = increase	Digital
P+	Upper pin of potentiometer (5V)	--	Both
D/CN	Wiper of potentiometer (analog) Decrease Pulse Width (digital) (internal pull-up in digital mode)	L = decrease (digital)	Both
P-	Lower pin of potentiometer (GND)	--	Analog
O-	Negative output to LOAD	--	Both
O+	Positive output to LOAD	--	Both
GND	Ground from power supply	--	Both
V+	Positive Power Supply	--	Both

Modes of Operation:

The Analog/Digital PWM Controller can be operated in analog or digital mode. The jumper labeled A/D is used to select between analog and digital inputs. Jumper PB is used to select between microcontroller mode and push button mode.

Table 1: Jumper Configuration

	Jumper Label	Position	Function
	A/D	Closed	Potentiometer (Analog Mode)
	A/D	Open	Digital Mode
	PB	Closed	Microcontroller Mode
	PB	Open	Pushbutton Mode

Note: All jumper setting changes take effect at power-up. Power down the board before changing the jumper settings.

Analog Mode:

When the board is configured for Analog Operation using the jumper, a varying voltage (0 – 5 V) level is converted to the pulse width at the output (0 – 100%). Any potentiometer from 1k Ω - 30 k Ω may be used for speed control.

There is a built-in dead-band for potentiometer operation that sets the duty cycle to:
 0% for any voltage level < 0.10 V.
 100% for any voltage level > 4.90 V.

This dead-band along with digital filtering ensures smooth and reliable operation even with dirty potentiometers.

Digital Mode:

There are two ways to operate in digital mode: Microcontroller Mode and Pushbutton Mode.

Microcontroller Mode:

In microcontroller mode, the UP and D/CN inputs are pulsed to control the duty cycle. There are 128 levels of PWM. For every rising edge of the UP [D/CN] line, the output pulse width is increased [decreased] by one level (approximately 0.8%). Once the pulse width reaches 0%, any further inputs on the D/CN line have no effect. Similarly, when the pulse width reaches 100%, any further inputs on the UP line have no effect.

Pushbutton Mode:

In pushbutton mode, the UP and D/CN inputs are designed for interfacing to push buttons. When the UP line is brought LOW, the duty cycle is continuously increased at a rate of ~ 33% per second. Similarly, when the D/CN line is brought low, the duty cycle is decreased at a rate of ~ 33% per second. Any additional increase [decrease] after the pulse width has reached 100% [0%] will have no effect on the output.

Automatic digital de-bouncing of the inputs is implemented in pushbutton mode. Spurious inputs are ignored.

Output Enable:

The output is enabled by default and is internally pulled up. Bringing this pin low immediately brings the PWM output to 0%. Allowing the pin to go back to high re-enables the PWM output at the previous duty cycle.

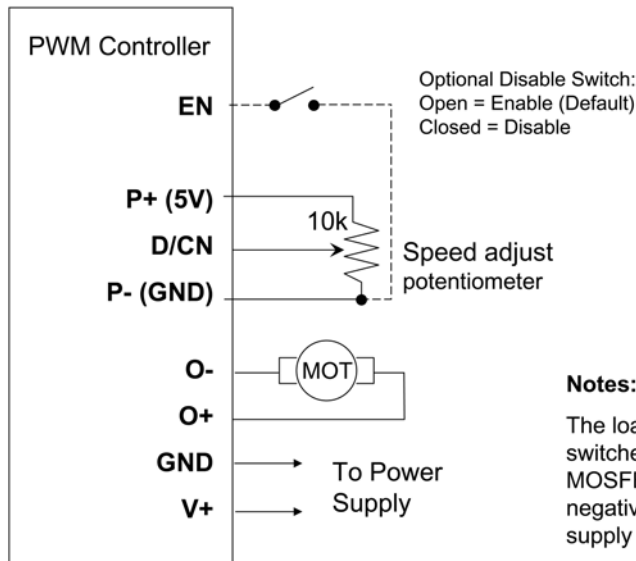
When in digital mode, the duty cycle may be changed by the UP and D/CN pins at all times, even in PWM output disabled mode. Thus, it is possible to turn off the output, change the duty cycle, and turn on the output again, but at the new duty cycle.

Soft Start (SPD-328-DS only):

The output is automatically ramped up back to the full PWM level at a rate of 100% per second. This reduces the stress placed on power supplies and mechanical linkages as motors come back up to speed, or as high temperature resistive loads heat up (such as light bulbs).

Connection Diagrams:

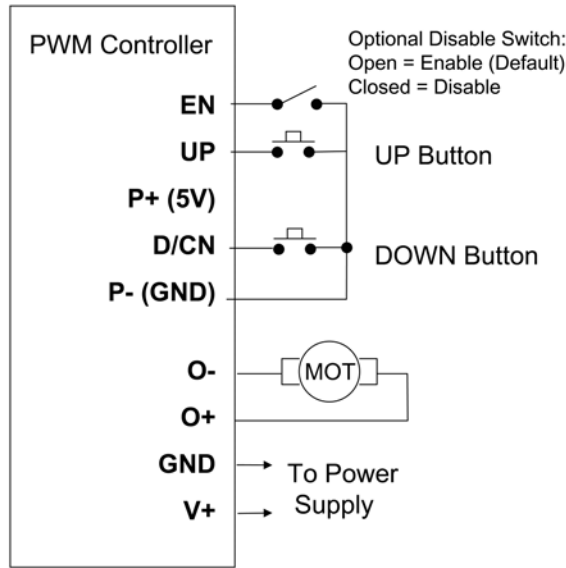
Analog Control Mode:



Notes:

The load's negative terminal is switched (grounded) via the MOSFET. Do not tie the load's negative terminal to power supply ground.

Push Button Interface Mode:

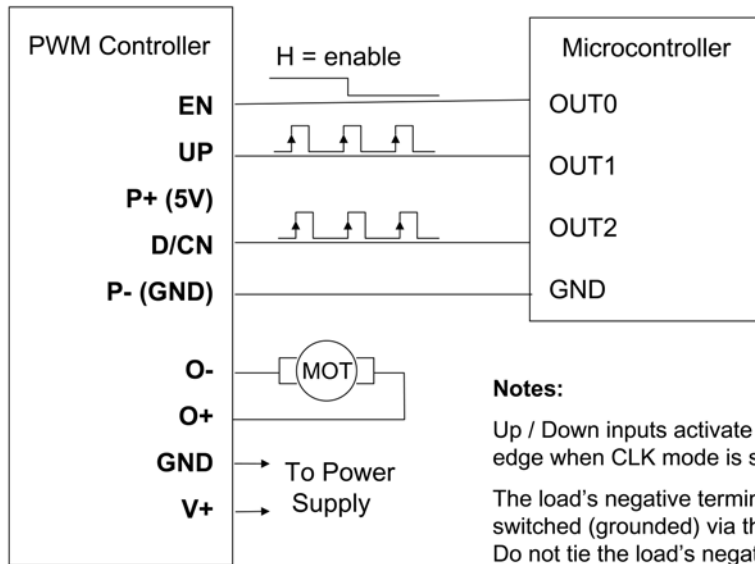


Notes:

Press and hold the UP button to increase the power. Press and hold the DOWN button to decrease the power.

The load's negative terminal is switched (grounded) via the MOSFET. Do not tie the load's negative terminal to power supply ground.

Microcontroller Interface Mode:



Notes:

Up / Down inputs activate on the rising edge when CLK mode is selected.

The load's negative terminal is switched (grounded) via the MOSFET. Do not tie the load's negative terminal to power supply ground.

Application Notes:

A fuse appropriately rated for the load device is required to ensure safe operation.

This controller is not reverse-polarity protected. **Ensure that it is wired correctly before applying power.** Always turn off the power supply before making any changes to the wiring.

PWM controllers switch currents at high frequencies to vary the average power to the load. This switching can cause undesirable RF interference. To minimize such interference, it is recommended to twist the input V+ and Ground wire pair as well as the Out+ and Out- wire pair.

Ensure that the controller has adequate air flow for proper cooling. If operating at high current levels for extended periods of time, a cooling fan may be necessary.

Use the shortest possible wiring between the load and controller, and between the controller and the power source. Ensure that the cables carrying the load current are adequately sized. If the wiring from the power source to the controller is more than 24 inches long, a 2200 uF 50V filter capacitor should be connected to the V+ and GND terminals of the PWM controller. Inadequate power supply filtering or other causes leading to a high impedance path to the power supply will result in higher losses in the filter capacitor and wiring, and may damage the load and/or controller.

The heat sink on the controller is electrically live. Do not connect anything to the heat sink, and do not use it as a mounting location. Use only the holes provided on the board itself for mounting.

30-Day Limited Warranty:

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